



On Efficiently Updating Singular Value Decomposition Based Reduced Order Models

Ralf Zimmermann

GAMM Workshop Applied and Numerical Linear Algebra

with Special Emphasis on Model Reduction

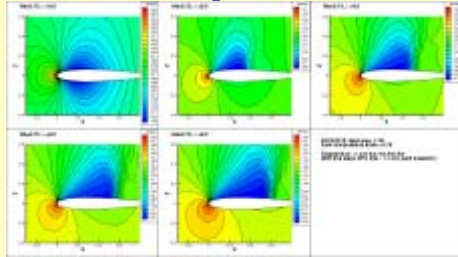
Bremen, Sep. 22.-23. 2011



DLR Deutsches Zentrum
für Luft- und Raumfahrt e.V.
in der Helmholtz-Gemeinschaft

The POD-based ROM approach

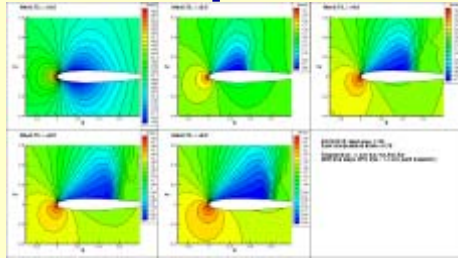
1. Input: CFD snapshots



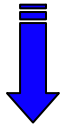
Flow solutions at m
different flow
conditions

The POD-based ROM approach

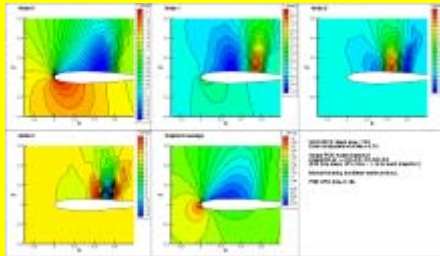
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Flow solutions at m different flow conditions



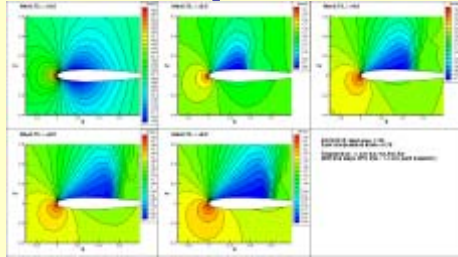
2. POD Basis



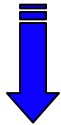
Orthonormal basis ordered by information content spanning the same space

The POD-based ROM approach

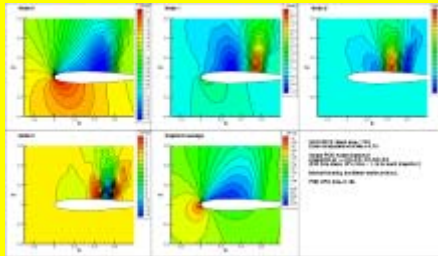
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Flow solutions at m different flow conditions



2. POD Basis



Orthonormal basis ordered by information content spanning the same space

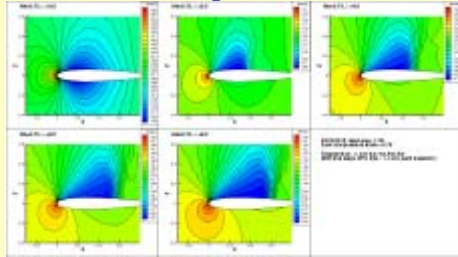


3. Order Reduction

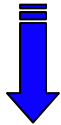
Select $\tilde{m} < m$ POD components with largest information content

The POD-based ROM approach

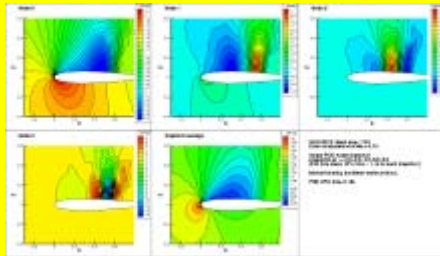
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Flow solutions at m different flow conditions



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Orthonormal basis ordered by information content spanning the same space



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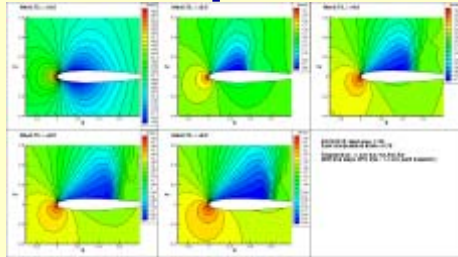


4. Prediction step

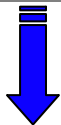
Determine POD-ROM coefficients by interpolation / solving low-order PDEs / least-squares optimization

The POD-based ROM approach

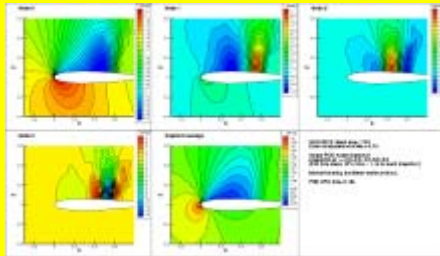
1. Input: CFD snapshots



Flow solutions at m different flow conditions



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Orthonormal basis ordered by information content spanning the same space



3. Order Reduction

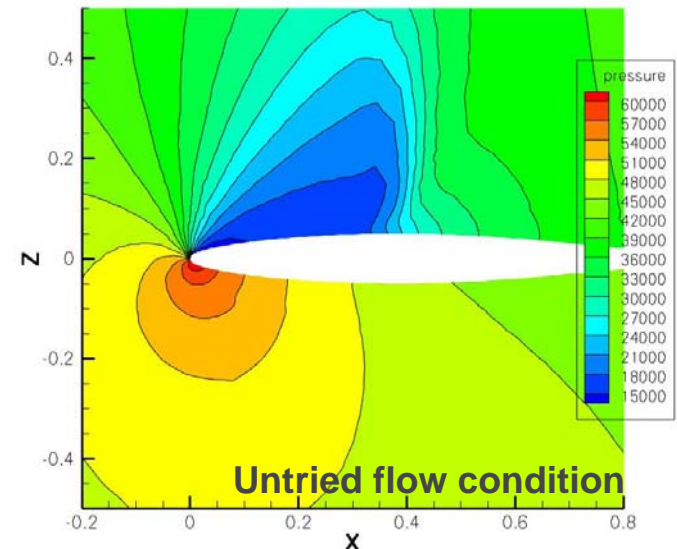
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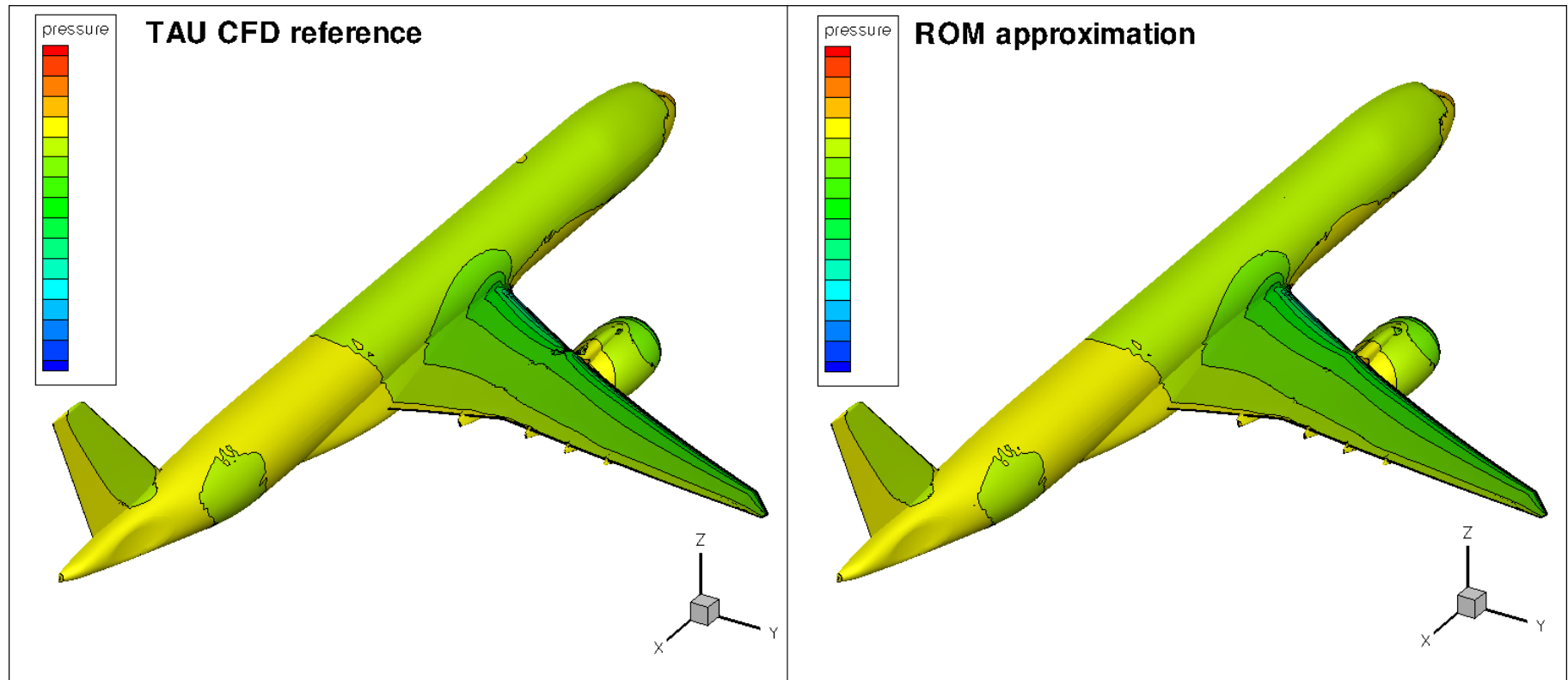
4. Prediction step

Determine POD-ROM coefficients by interpolation / solving low-order PDEs / least-squares optimization

5. Output: approximated flow field



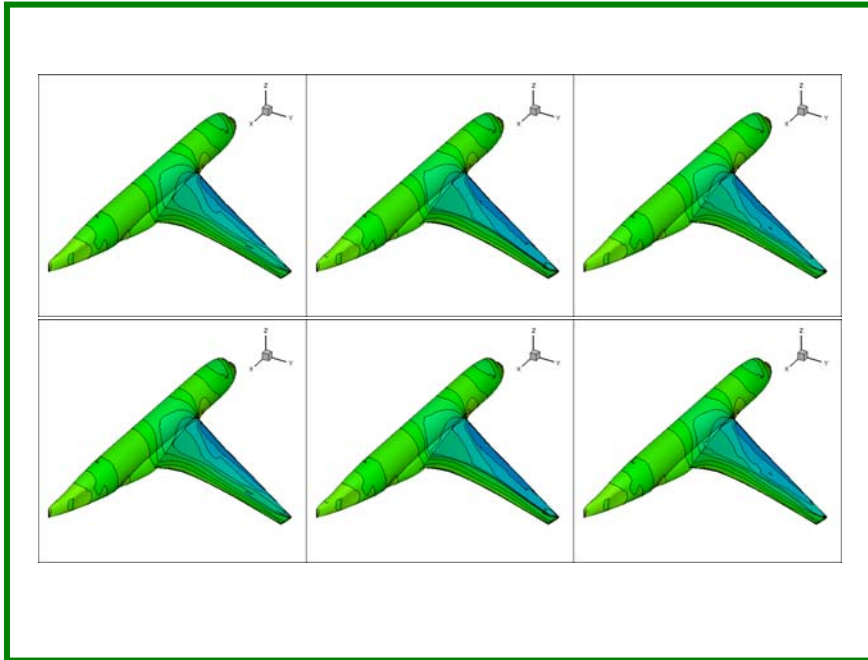
POD based reduced order models are a powerful tool...



Industrial aircraft configuration
ROM Speed-up factor > 300

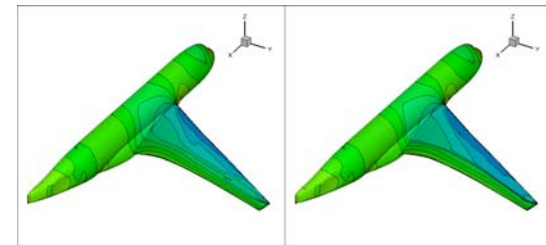
Grid size ~**9Mio**, subsonic $Ma = 0.2$
Snapshot data at $AoA = -1^\circ, 0^\circ, 1^\circ, 2^\circ$
Prediction at $AoA = 7^\circ$ (**Extrapolation!**)

... but treating *large* snapshots may become a challenge!



POD/SVD representation known

+



Incoming new snapshots

How to compute POD/SVD of augmented data set efficiently?

Nomenclature

Snapshot matrix : $Y_m = (W^1, \dots, W^m) \in R^{n \times m}$

Snapshot average : $A_m = \frac{1}{m} \sum_{j=1}^m W^j$

Centering : $\bar{Y}_m = Y_m - A_m \mathbf{1}^T = (W^1 - A_m, \dots, W^m - A_m) =: (\bar{W}^1, \dots, \bar{W}^m),$

SVD : $\bar{Y}_m = U \Sigma V^T$

Relative Information content : $ric(r_m) = \frac{\sum_{i=1}^{r_m} \sigma_i^2}{\sum_{i=1}^m \sigma_i^2}, \quad r_m \leq m-1$

Reduced-order representation

Discard columns corresponding to small singular values:

$$\bar{Y}_m \approx U_m \Sigma_m V_m^T,$$

$$U_m = (U^1, \dots, U^{r_m}) \in R^{n \times r_m}, \quad V_m = (V^1, \dots, V^{r_m}) \in R^{m \times r_m}, \quad \Sigma_m = \begin{pmatrix} \sigma_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \sigma_{r_m} \end{pmatrix}$$

Definition:

The data set $(U_m, \Sigma_m, V_m, A_m, n, m, r_m)$

is called reduced-order model of order r_m of Y_m .

The ratio $\frac{r_m}{m}$ is called the compression rate.

The SVD basis update problem

Given: ROM $(U_m, \Sigma_m, V_m, A_m, n, m, r_m)$ of $Y_m \in R^{n \times m}$.

p new snapshot observations $(W^{m+1}, \dots, W^{m+p})$

Task: Compute ROM $(U_{m+p}, \Sigma_{m+p}, V_{m+p}, A_{m+p}, n, m+p, r_{m+p})$
of Y_{m+p} .

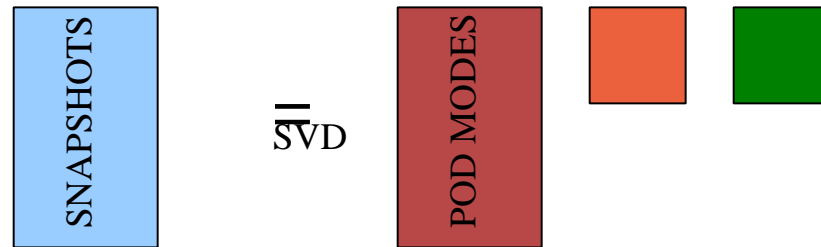
Requirement:

- use only the previous stage ROM and the incoming snapshots!
- $n \gg m$! Keep computational costs depending on n as low as possible

Objective

Efficient SVD basis update

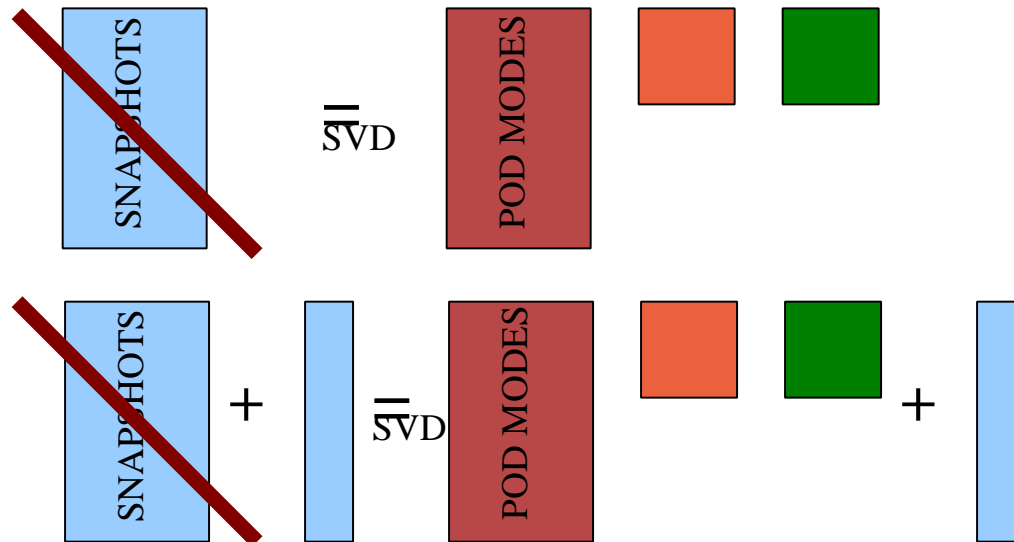
- Update SVD basis without having to store the **initial** snapshots



Objective

Efficient SVD basis update

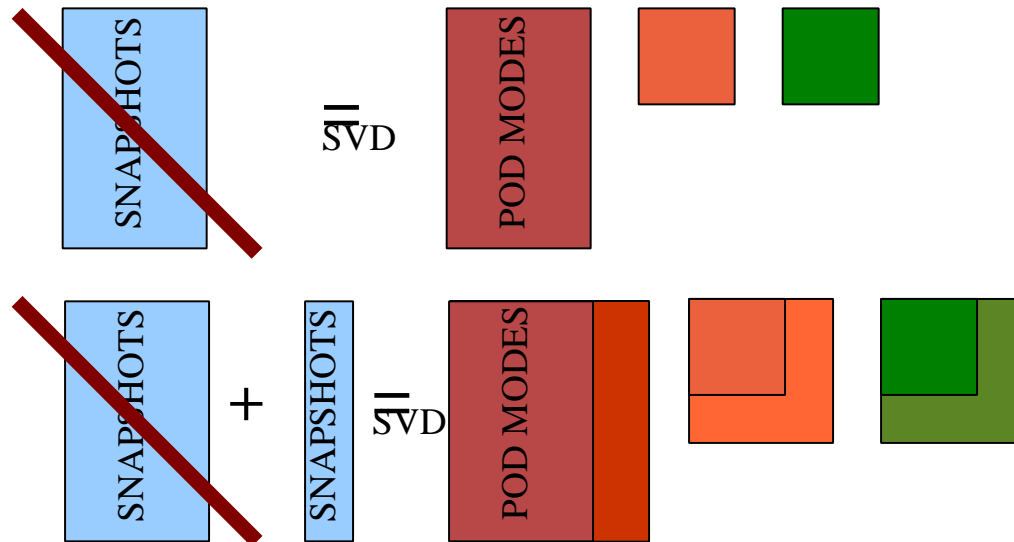
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Objective

Efficient SVD basis update

- Update SVD basis without having to store the **initial** snapshots



SVD basis update strategies

Updating the snapshot mean

Shift vector:
$$T_{m+p} := \frac{1}{m+p} \left(pA_m - \sum_{i=m+1}^{m+p} W^i \right)$$

$$\Rightarrow A_{m+p} = A_m - T_{m+p}$$

Shift update snapshots to the previous-stage center:

$$\bar{W}^{m+i} := W^{m+i} - A_m, \quad i = 1, \dots, p$$

To do: Decompose

$$\bar{Y}_{m+p} = (\bar{Y}_m, \bar{W}) + T_{m+p} 1_{m+p}^T \approx U_{m+p} \Sigma_{m+p} V_{m+p}^T,$$

SVD basis update strategies

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Shift update snapshots to the previous-stage center:

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start here

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$$\bar{Y}_{m+p} = (\bar{Y}_m, \bar{W}) + T_{m+p} 1_{m+p}^T \approx U_{m+p} \Sigma_{m+p} V_{m+p}^T,$$

SVD basis update strategies (A): two-steps SVD^{1,2}

Setting $X = (\bar{Y}_m, 0^{n \times p}), B^T = (0^{p \times m}, I^{p \times p})$

it holds

$$(\bar{Y}_m, \bar{W}) = X + \bar{W}B^T \quad \text{and} \quad X \approx U_m \Sigma_m (V_m^T, 0^{r_m \times p})$$

¹ M. Brand: "Fast low-rank modifications of the thin SVD", *Lin. Alg. and its Appl.* 415, 2006

² P. Hall et al.: "Merging and splitting eigenspace models", *IEEE Trans. Pattern analysis and Machine Intelligence*, 22(9), 2000

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rank-p SVD update problem

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Factoring out orthogonal components:

$$X + \bar{W}B^T = (U_m, \bar{W}) \begin{pmatrix} \Sigma_m & 0 \\ 0 & I^{p \times p} \end{pmatrix} \begin{pmatrix} (V_m^T, 0^{r_m \times p}) \\ (0^{p \times m}, I^{p \times p}) \end{pmatrix}$$

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Factoring out orthogonal components:

$$X + \bar{W}B^T = (U_m, P_{orth}) \begin{pmatrix} \Sigma_m & U_m^T \bar{W} \\ 0 & P_{orth}^T P \end{pmatrix} \begin{pmatrix} (V_m^T, 0^{r_m \times p}) \\ (0^{p \times m}, I^{p \times p}) \end{pmatrix}$$

where $P = \bar{W} - U(U_m^T \bar{W}), \quad P_{orth} = \text{orth}(P)$ **e.g. via Gram Schmidt**

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orthonormal
columns

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Factoring out orthogonal components:

$$X + \bar{W}B^T = \underbrace{(U_m, P_{orth})}_{\text{orthonormal columns}} \begin{pmatrix} \Sigma_m & U_m^T \bar{W} \\ 0 & P_{orth}^T P \end{pmatrix} \begin{pmatrix} (V_m^T, 0^{r_m \times p}) \\ (0^{p \times m}, I^{p \times p}) \end{pmatrix}$$

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size $(r_m + p) \times (r_m + p)$

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Factoring out orthogonal components:

$$X + \bar{W}B^T = [(U_m, P_{orth})\tilde{U}] \tilde{\Sigma} \left[\tilde{V}^T \begin{pmatrix} (V_m^T, 0^{r_m \times p}) \\ (0^{p \times m}, I^{p \times p}) \end{pmatrix} \right]$$

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SVD basis update strategies (A): two-steps SVD^{1,2}

Repeat for shifting to new center:

$$\bar{Y}_{m+p} = (\bar{Y}_m, \bar{W}) + T_{m+p} \mathbf{1}_{m+p}^T \approx U_{m+p} \Sigma_{m+p} V_{m+p}^T,$$

SVD now known

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SVD basis update strategies (A): two-steps SVD^{1,2}

Comments:

- ‘re-orthogonalization’ expensive, additional (large-scale) SVD required
- less robust via Gram-Schmidt

$$P = \bar{W} - U(U_m^T \bar{W}), \quad P_{orth} = \text{orth}(P)$$

- Parallelization is more involved

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SVD basis update strategies (B): EVD³+SVD

Objective: $\bar{Y}_{m+p} = (\bar{Y}_m, \bar{W}) + T_{m+p} 1_{m+p}^T \approx U_{m+p} \Sigma_{m+p} V_{m+p}^T,$

First step: Compute SVD of (\bar{Y}_m, \bar{W})

Reduce to symmetric EVD

$$(\bar{Y}_m, \bar{W})^T (\bar{Y}_m, \bar{W}) = \begin{pmatrix} \bar{Y}_m^T \bar{Y}_m & \bar{Y}_m^T \bar{W} \\ \bar{W}^T \bar{Y}_m & \bar{W}^T \bar{W} \end{pmatrix}$$

³ Generalize ideas from: J.R. Bunch, C.P. Nielsen: “Updating the singular value decomposition”, *Numer. Math.* 31, 1978

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First step: Compute SVD of (\bar{Y}_m, \bar{W})

Reduce to symmetric EVD

$$(\bar{Y}_m, \bar{W})^T (\bar{Y}_m, \bar{W}) \approx \begin{pmatrix} V_m \Sigma_m^2 V_m^T & V_m \Sigma_m U_m^T \bar{W} \\ \bar{W}^T U_m \Sigma_m V_m^T & \bar{W}^T \bar{W} \end{pmatrix}$$

**Exploit previous
stage SVD**

³ Generalize ideas from: J.R. Bunch, C.P. Nielsen: “Updating the singular value decomposition”, *Numer. Math.* 31, 1978

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First step: Compute SVD of (\bar{Y}_m, \bar{W})

Reduce to symmetric EVD

$$(\bar{Y}_m, \bar{W})^T (\bar{Y}_m, \bar{W}) \approx \begin{pmatrix} V_m & 0 \\ 0 & I^{p \times p} \end{pmatrix} \begin{pmatrix} \Sigma_m^2 & \Sigma_m U_m^T \bar{W} \\ \bar{W}^T U_m \Sigma_m & \bar{W}^T \bar{W} \end{pmatrix} \begin{pmatrix} V_m^T & 0 \\ 0 & I^{p \times p} \end{pmatrix}$$

factor out

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SVD basis update strategies (B): EVD³+SVD

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First step: Compute SVD of (\bar{Y}_m, \bar{W})

Reduce to symmetric EVD

$$(\bar{Y}_m, \bar{W})^T (\bar{Y}_m, \bar{W}) \approx \begin{pmatrix} V_m & 0 \\ 0 & I^{p \times p} \end{pmatrix} \begin{pmatrix} \Sigma_m^2 & \Sigma_m U_m^T \bar{W} \\ \bar{W}^T U_m \Sigma_m & \bar{W}^T \bar{W} \end{pmatrix} \begin{pmatrix} V_m^T & 0 \\ 0 & I^{p \times p} \end{pmatrix}$$

size $(r_m + p) \times (r_m + p)$

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First step: Compute SVD of (\bar{Y}_m, \bar{W})

Reduce to symmetric EVD

$$(\bar{Y}_m, \bar{W})^T (\bar{Y}_m, \bar{W}) \approx \begin{pmatrix} V_m & 0 \\ 0 & I^{p \times p} \end{pmatrix} (\tilde{Q} \tilde{\Lambda} \tilde{Q}^T) \begin{pmatrix} V_m^T & 0 \\ 0 & I^{p \times p} \end{pmatrix}$$

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Reduce to symmetric EVD

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Compute left singular vectors via

$$\hat{U} = (U_m \Sigma_m, \bar{W}) \tilde{Q} \sqrt{\tilde{\Lambda}^{-1}}$$

³ Generalize ideas from: J.R. Bunch, C.P. Nielsen: "Updating the singular value decomposition", *Numer. Math.* 31, 1978

SVD basis update strategies (B): EVD³ + SVD

Use Brand's method for shifting to new center:

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SVD now known

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SVD basis update strategies (C): one-step EVD

Objective: $\bar{Y}_{m+p} = (\bar{Y}_m, \bar{W}) + T_{m+p} \mathbf{1}_{m+p}^T \approx U_{m+p} \Sigma_{m+p} V_{m+p}^T,$

Let $X := (\bar{Y}_m, \bar{W}) + T_{m+p} \mathbf{1}_{m+p}^T \in R^{n \times (m+p)}$

Reduce to symmetric EVD,

exploit previous stage SVD in matrix products

$$X^T X = \tilde{Q} \tilde{\Lambda} \tilde{Q}^T \in R^{(m+p) \times (m+p)}$$

Compute left singular vectors via

$$U_{m+p} = X \tilde{Q} \sqrt{\tilde{\Lambda}^{-1}}$$

SVD basis update strategies (B) and (C)

Comments:

- Straight forward parallelization!
(only standard matrix products required in parallel)

Analysis of Computational costs

➤ Count nmp flops for matrix product AB , $A \in R^{n \times m}, B \in R^{m \times p}$

➤ **Strategy (B) is more efficient than strategy (A):**

$$\begin{aligned}\text{flops(A)} - \text{flops(B)} &= \left(r_m p + \frac{1}{2} (p^2 + p) \right) n + O(\text{orth}(P)) \\ &= O((mp + p^2)n)\end{aligned}$$

Analysis of Computational costs

The ranking of Strategy (B) vs. (C) depends on the compression rate!

➤ Assumption:

$$r_{m+p} = r_m + p = xm + p, \quad x = \frac{r_m}{m} \text{ (compression rate)}$$

➤ Then the computational costs differ by

$$\text{flops(C)} - \text{flops(B)} = n \left((x - 2x^2)m^2 + (2 - 3x)(mp + m) - p^2 - p - 2 \right)$$

Analysis of Computational costs

The ranking of Strategy (B) vs. (C) depends on the compression rate!

- Solving the quadratic equation shows that Strategy (B) is more efficient than Strategy (C) if

$$0 < x < \frac{1}{4m} \left(m - 3(p+1) + \sqrt{10m(p+1) + m^2 + p^2 + 10p - 7} \right)$$

- In practical implementations, use switch to select the most efficient update strategy.

Analysis of Computational costs

Rules of thumb:

- For highly compressed models, Strategy (B) is more efficient than Strategy (C)
- For weakly compressed models, the opposite holds true

More precisely

- Strategy (B) is more efficient than Strategy (C), if $x \leq \frac{1}{2}$
and $m \geq 2p + 1$.
- Strategy (C) is more efficient than Strategy (B), if $x \geq \frac{2}{3}$.

Example: Updating SVDs of Random matrices

$$Y \in R^{n \times m}, W \in R^{n \times p}, n = 100,000, m = 500, p = 100$$

Method	Reconstruction error	time (sec)
Strategy (A), SVD-orth	2.504e-12	7.88
Strategy (A), QR-orth	2.333e-12	8.15
Strategy (B)	2.342e-12	6.32
Strategy (C)	2.279e-12	4.42

➤ Uncompressed models $r_m = m - 1 = 499$, $r_{m+p} = 599$

Example: Updating SVDs of Random matrices

$$Y \in R^{n \times m}, W \in R^{n \times p}, n = 100,000, m = 500, p = 100$$

Method	Reconstruction error	time (sec)
Strategy (A), SVD-orth	92.21	4.18
Strategy (A), QR-orth	92.21	4.23
Strategy (B)	92.21	1.93
Strategy (C)	93.41	3.54

➤ Compression level $r_m = 200$, $r_{m+p} = 200$, $x = \frac{r_m}{m} = 0.4$

Summary

- The update strategies following the symmetric EVD approach are more efficient than the SVD update known from literature (Brand, Hall et al.) (Assumption: $n \gg m$)
- Industrial point of view: SVD/EVD performed by '**black box function**'
- Most efficient: choose method depending on the compression rate
- The examples suggest that all methods share a similar level of accuracy (SVD-approach may suffer from orthogonal out-factoring, EVD-approaches may suffer from squaring the condition number)

Summary

- For details and additional references, see:
- “A comprehensive comparison of various algorithms for efficiently updating singular value decomposition based reduced order models”, DLR IB 124-2011/3**

Freely available at DLR's electronic library:

<http://elib.dlr.de/70251>

Thank you for your attention!

